

# TDR-1000 GUIDED WAVE RADAR Quick Start Guide



# INSTALLATION, OPERATION & MAINTENANCE MANUAL

# SAFETY INFORMATION

Before installing the TDR-1000 model, please read these instructions and familiarize yourself with the requirements and functions. If any questions or problems arise during the installation, please contact Bindicator® Applications at 1-800-778-9242.

The TDR-1000 model must only be installed and operated as described in this operating instruction. Please note that other action can cause damage for which Bindicator® does not take responsibility. If the model is not installed correctly or used in approved applications, dangers may arise such as product overflow.

Ensure that all personnel installing, wiring, and calibrating this device are suitably qualified.

Observe all local and national electrical codes for the wiring of this device.

The TDR-1000 level gauge is designed solely for measuring the distance, level and volume of liquids, solids and particulate materials.

Special codes and regulations apply to its use in hazardous areas.

Responsibility as to suitability and intended use of these level gauges rests solely with the user.

Improper installation and operation of our level gauges may lead to loss of warranty.

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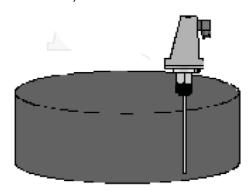
### 1.0 RANGE OF USE

The TDR-1000 level gauging system is a 2 wire transmitter, designed to measure the distance, level and volume of liquids, slurries, solids and particulate materials. It can be operated on storage and process tanks.

# 2.0 Description

The measuring system consists of the sensor and the signal converter. The compact signal converter contains the TDR measuring circuit and the entire signal processing system, including the provision of a standardized output signal (4 - 20 mA or digital interface).

Converter Connection
1.5 MNPT; electrical 1" G (grommet open lead) Connection with Pressure tight Signal feed through



# 3.0 Measured variable (distance, level, volume)

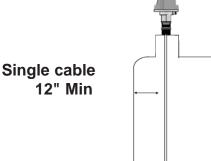
The primary measured variable is the distance between the tank mounting flange and a reflecting surface (surface of the product measured). The output represents the difference between the primary measured variable and the length of the sensor.

# 3.1 Measuring range (to 78 ft)

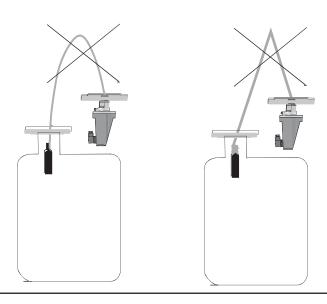
The measuring range will depend on the sensor length, the reflection properties of the tanks contents, the installation position, and the presence of any interfering reflection

# 4.0 Mounting, please refer to the following guidelines:

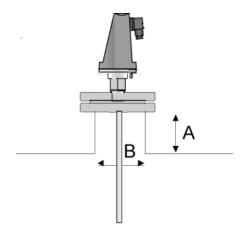
ENSURE THE SENSOR LENGTH DOES NOT EXCEED THE INTERNAL DEPTH OF THE SILO, TANK OR VESSEL.



# BE CAREFUL NOT TO BEND OR KINK CABLES TOO MUCH



# 4.2 Mounting on a nozzle

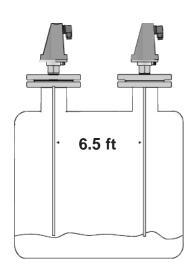


Avoid nozzle size higher than 5.9", especially when B < 3.1".

Try to ensure A does not exceed B.

# 4.3 Interference between two TDR-1000

There must be at least 6.5ft between devices if installed in the same vessel.



## 5.0 Electrical connection

The electrical connection for the power supply is made in the terminal compartment of the signal converter - 18-35VDC.

In case of installation in hazardous areas, only certified intrinsically safe equipment may be connected to the TDR-1000.

### 1. Connector:

Terminals: 3 poles + ground. Wire cross-section max  $0.059\text{m}^2$  (1.5 mm²) ≈(AWG 16). pCable entries: M25x1.5 (PG11). Standard cable gland: cable clamping area = 0.315 - 0.39 in

(8-10 mm). IP65

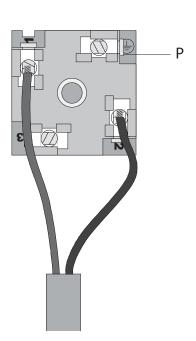
**Signal cable shielding:** No shielding needed.

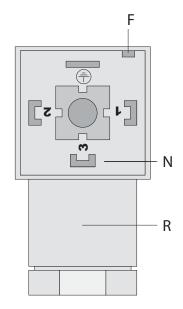
# Power supply:

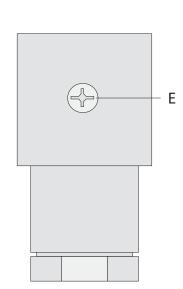
- 1. Remove the screw **P** and lift off the connector from the signal converter.
- 2. Put a screwdriver in **F** and separate **N** from **R**.
- 3. Connect the current loop to terminal 1 and 2 (there's no polarity to respect). Use ferrules to protect cable ends. The terminal 3 and **E** remain non-connected.
- 4. Re-assemble N and R.
- 5. Put the seal in place, connect **R** to the signal converter tighten and screw **P**.

The terminal **E** is not connected with the signal connector housing or with the flange system of the instrument.

For standard and Ex applications only the intrinsically safe 2-wire loop must be connected to the terminals 1 and 2. The terminal **E** as well as terminal 3 remains non-connected.







# 6.0 Technical Specifications

Function: Level, distance and volume measurement of liquids and solids.

Measuring Range: Flexible probe: to 78ft

> Deadband: Top: 15.8in Dieletric < 10 11.8in Dieletric > 10

Deadband: Bottom: 14.25in

Counter Weight Diameter.: 1.575in; length 10.25in (Weight is tapped with 1/2" - 13 to allow tethering or anchoring)

+/- 0.6in Accuracy: Repeatability: 0.04in **Dielectric Constant:** > 2.3

**Probe Materials:** Flexible cable 316SS

**Operating Pressure:** 232 psi

Flange Temperature: -22° to 194°F Electronics Temperature: -22° to 131°F Connection: 1.5" MNPT

**Protection Category:** IP66; Nema 4X

**Power Supply:** 24VDC (18 to 35VDC)

4/20mA current loop into max. of 750 Ohms Output:

Communication: HART protocol

Approvals: CE

Weight: Without probe 4.4lbs (2Kgs)

Materials of

Construction: Housing: Aluminium with white epoxy coating

Cable and Weight: 316 SS

Gaskets: Buna N

**Electrical Connection** 

**M16 CONNECTOR** 

Terminals: Max wire size 16AWG (1.5mm)

Cable Entries: 1 x M16 x 1.5 (with standard cable gland: cable

clamping area =0.137 - 0.315in(3.5-8mm)).

**Electrical Signal Output** 

**Electrical Connection:** Two wire

**Power Supply:** 18 to 35 VDC

**Current Output:** 4/20mA

**Environment** 

Ambient Temperature: -22° to 131°F

**Protection Category to** 

EN 60529 / IEC 529: IP66, Nema 4X

# 7.0 Programmed Information

CHECK LIST PARAMETERS TDR-1000 to: Device No	Comm No	Date:
Location Contact person	Telephone	
Remarks:		
Menu item	Changed on	
Fct. Configuration parameters (customer)		
1.1.1 Tank height	:	<u>:                                    </u>
1.1.2 Dead zone		<u>:</u>
1.1.3 Time constant	:	<u> </u>
1.1.6 Probe length	:	<u> </u>
1.2.4 Length unit		<u> </u>
1.2.6.1 Unit name		<u> </u>
1.2.6.2 Unit factor	:	<u> </u>
1.2.5 Volume unit		<u> </u>
1.3.1 Current output, function		<u> </u>
1.3.2 Current output, range/error		<u> </u>
1.3.3 Min. scale for current	:	
1.3.4 Max. scale for current		
1.3.5 Error delay		
1.4.4 Tag name		
1.5.1 Detection delay	:	
1.6.2 Address Threshold_		<u>:</u>
1.1.1 Probe type 1.1.2 Offset of measure	:	<u>:</u>
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# **Notes**



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